Introducing Global and Local Walsh Wavelet Transform for Texture Pattern Based Image Retrieval

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Summary

The theme of the work presented in the paper is novel texture pattern based image retrieval techniques using ternary image maps and two different non-sinusoidal orthogonal Walsh wavelet transforms namely Global Walsh Wavelet Transform and Local Walsh Wavelet Transform. Different texture patterns namely '64-pattern' and '256-pattern' are generated using both the Walsh wavelet transform matrices giving rise to global and local texture patterns. The generated texture patterns are then compared with the ternary image maps to generate the feature vector based on structural matching as the matching number of ones, zeros, minus ones per Walsh wavelet texture pattern. Here total 4 variations of the proposed novel image retrieval methods using texture patterns are considered with two different texture patterns and two different ways to generate these texture patterns (Global and Local). The proposed texture content based image retrieval (CBIR) techniques are tested on the image database with help of 55 queries (randomly selected 5 from each of 11 image categories) fired on image database. The performance comparison of texture pattern based CBIR methods is done with help of precision-recall crossover points.

Key words:

CBIR; Walsh Transform; Wavelet Transform; Texture; Patterns; Ternary Image Maps; Global & Local Textures

1. Introduction

Today the information technology experts are facing technical challenges to store/transmit and index/manage image data effectively to make easy access to the image collections of tremendous size being generated due to large numbers of images generated from a variety of sources (digital camera, digital video, scanner, the internet etc.). The storage and transmission is taken care of by image compression [4,7,8]. The image indexing is studied in the perspective of image database [5,9,10,13,14] as one of the promising and important research area for researchers from disciplines like computer vision, image processing and database areas. The hunger of superior and quicker image retrieval techniques is increasing day by day. The significant applications for CBIR technology could be listed as art galleries [15,17], museums, archaeology [6], architecture design [11,16], geographic

information systems [8], weather forecast [8,25], medical imaging [8,21], trademark databases [24,26], criminal investigations [27,28], image search on the Internet [12,22,23]. The paper attempts to provide better and faster image retrieval techniques.

1.1 Content Based Image Retrieval

For the first time Kato et.al. [7] described the experiments of automatic retrieval of images from a database by colour and shape feature using the terminology content based image retrieval (CBIR). The typical CBIR system performs two major tasks [19,20] as feature extraction (FE), where a set of features called feature vector is generated to accurately represent the content of each image in the database and similarity measurement (SM), where a distance between the query image and each image in the database using their feature vectors is used to retrieve the top "closest" images [19,20,29].

For feature extraction in CBIR there are mainly two approaches [8] feature extraction in spatial domain and feature extraction in transform domain. The feature extraction in spatial domain includes the CBIR techniques based on histograms [8], BTC [4,5,19], VQ [24,28,29]. The transform domain methods are widely used in image compression, as they give high energy compaction in transformed image [20,27]. So it is obvious to use images in transformed domain for feature extraction in CBIR [26]. But taking transform of image is time consuming. Reducing the size of feature vector using pure image pixel data in spatial domain and getting the improvement in performance of image retrieval is shown in [1,2,3]. But the problem of feature vector size still being dependent on image size persists in [1,2,3]. Here the query execution time is further reduced by decreasing the feature vector size further and making it independent of image size. Many current CBIR systems use the Euclidean distance [4-6,11-17] on the extracted feature set as a similarity measure. The Direct Euclidian Distance between image P and query image Q can be given as equation 1, where Vpi and Vqi are the feature vectors of image P and Query image Q respectively with size 'n'.

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$$ED = \sqrt{\sum_{i=1}^{n} \left(Vpi - Vqi\right)^2} \tag{1}$$

2. Generation of Ternary Image Maps

For generating ternary image maps, the image maps of colour image are generated using three independent red (R), green (G) and blue (B) components of image to calculate three individual colour thresholds and one overall luminance threshold [35]. Let $X=\{R(i,j),G(i,j),B(i,j)\}$ where i=1,2,...,m and j=1,2,...,n; be an m×n color image in RGB space. Let the individual colour thresholds be TR, TG and TB which could be computed as per the equations given below as 2, 3 and 4. Let the luminance threshold T be as given by equation 5.

$$TR = \frac{1}{m * n} \sum_{i=1}^{m} \sum_{j=1}^{n} R(i, j)$$
(2)

$$TG = \frac{1}{m^* n} \sum_{i=1}^{m} \sum_{j=1}^{n} G(i, j)$$
(3)

$$TB = \frac{1}{m * n} \sum_{i=1}^{m} \sum_{j=1}^{n} B(i, j)$$
(4)

$$T = \frac{TR + TG + TB}{3} \tag{5}$$

The ternary image maps are used for comparison with texture patterns generated using Walsh wavelet transform matrices. Here first for each component (R, G, and B), the individual colour threshold intervals (lower-Tshl, and higher-Tshh) are calculated as shown in equations 6, 7 and 8.

$$Tshrl = TR - |TR - T| \quad , \quad Tshrh = TR + |TR - T| \tag{6}$$

$$Tshgl = TG - |TG - T| \quad , \quad Tshgh = TG + |TG - T| \tag{7}$$

$$Tshbl = TB - |TB - T| \quad , \quad Tshbh = TB + |TB - T| \tag{8}$$

Then the individual color plane global ternary image maps are computed (TMr, TMg and TMb) as given in equations 9, 10 and 11. If a pixel value of respective color component is greater than the respective higher threshold interval (Tshh), the corresponding pixel position of the image map gets a value 'one'; else if the pixel value is lesser than the respective lower threshold interval (Tshl), the corresponding pixel position of the image map gets a value of 'minus one'; otherwise it gets a value 'zero'.

$$TMr(i, j) = \begin{cases} 1, & \text{if } .R(i, j) > Tshrh \\ 0, & \text{if } .Tshrl <= R(i, j) <= Tshrh \\ -1, & \text{if } .R(i, j) < Tshrl \end{cases}$$
(9)

$$TMg(i, j) = \begin{cases} 1, & \text{if } .G(i, j) > Tshgh \\ 0, & \text{if } .Tshgl <= G(i, j) <= Tshgh \\ -1, & \text{if } .G(i, j) < Tshgl \end{cases}$$
(10)

$$TMb(i, j) = \begin{cases} 1, & \text{if } .B(i, j) > Tshbh \\ 0, & \text{if } .Tshbl <= B(i, j) <= Tshbh \\ -1, & \text{if } .B(i, j) < Tshbl \end{cases}$$
(11)

3. Generation of Wavelet Transforms

Using the base transform matrix, two different nonsinusoidal orthogonal wavelet transforms are generated namely Global Wavelet Transform and Local Wavelet Transform. These wavelet transforms are used for generating texture patterns.

3.1 Global Wavelet Transform Generation

To generate a square Global Wavelet transform of order "2P", respective base transform matrices of size 2x2 and PxP are used. First each column of the 2x2 base transform is repeated P times. The last (P-1) rows of the PxP base transform matrix are copied into the wavelet transform starting from third row of the wavelet transform. Then the last (P-1) rows of the PxP base transform are copied into the wavelet transform starting from the transform starting from (P+2)th row and (P+1)th column of the wavelet transform. The remaining elements of the wavelet transform matrix are made equal to zero. The obtained matrix is normalized in order to make it an orthogonal transform matrix. Figure 1(a) shows 2x2 base transform matrix and figure 1(b) shows Global Wavelet transform of size 2Px2P.

B 11	B 12
B 21	B22

Figure 1(a). 2x2 Base Transform

							l ^{at} column	of B				2nd colu	mn of B
					Ŧ	Rep	eated P tin	nes		F	lepeated P	times	
					j,	B11	Bu	•••	Bu	B12	B12	•••	B12
						B21	B21	237.0	B21	B22	B22	0.17.5	B22
M11 M21	M ₁₂ M ₂₂		M _{1 (7-1)} M _{2 (7-1)}	M _{1P} M _{2P}		M ₂₁	M22	•••	M _{2P}	0	0	1227	0
M31	M32		M3 (P-1)	Мар		Mai	M32		Map	0	0		0
:	•									0	0		0
Mpi	M_{P2}		M _{P (P-1)}	Mpp	ľ	M _{P1}	M_{P2}		Mpp	0	0		0
	PxP Tr	ransform m	atrix		F	0	0	215	0	M21	M22	822 7	M _{2P}
						0	0	215	0	Mai	M ₃₂		Map
					F	0	0		0				
						0	0		0	Mpi	Mp2		Mpp

Figure 1(b). 2Px2P Global Wavelet Transform

3.2 Local Wavelet Transform Generation

To generate a square local Global Wavelet transform of order "2P", respective base transform matrix of size PxP is used. First each column of the PxP base transform is repeated twice. In the proceeding rows, the values of the elements of wavelet transform are set as 1 and -1 diagonally as shown in figure 2(b). The remaining elements of the wavelet transform matrix are made equal to zero. The obtained matrix is normalized in order to make it an orthogonal transform matrix. Figure 2(a) shows PxP base transform matrix and figure 2(b) shows Local Wavelet transform of size 2Px2P.

M ₁₁	M ₁₂	 M _{1 (P-1)}	M _{1P}
M ₂₁	M ₂₂	 M _{2 (P-1)}	M_{2P}
M _{P1}	M _{P2}	 M _{P (P-1)}	M _{PP}

Figure 2(a). PxP Base Transform

4. Texture Pattern Generation

Using the Walsh transform [21,22,26,36], two different non-sinusoidal orthogonal wavelet transforms are

generated namely Global Walsh Wavelet transform and Local Walsh Wavelet Transform. With the help of these Wavelet transform matrices assorted texture patterns [30-34,37,38] namely 64-pattern and 256-pattern are generated. To generate N^2 texture patterns (N^2 -pattern) texture patterns, NxN transform matrix is considered and the element wise multiplication of each row of the transform matrix is taken with all possible rows of the same matrix (consideration of one row at a time gives one pattern). The texture patterns obtained are orthogonal in nature.

4.1 Global Wavelet Transform Generation

The 64 and 256 global Walsh texture patterns are generated using Global Walsh Wavelet transform matrices of size 8x8 and 16x16 respectively. The 8x8 global Walsh wavelet transform matrix is shown as in figure 3(a), each row of this matrix is considered one at a time and is multiplied with all rows of the same matrix to generate 64 Walsh texture patterns. Figure 3(b) shows first 16 (of total 64 texture patterns) texture patterns of the 64-pattern Global Walsh texture set where black colour represent the values '1' in the pattern, grey colour represents the value '0' and values '-1' are represented by white colour. The obtained Walsh texture patterns then are resized as the size of image for which texture features have to be extracted.

	1 st col	umn of M	2 nd colur	nn of M	3rd colum	n of M			Pth colur	nn of M
. +	Repeate	d 2 times	Repeated	1 2 times	Repeate	d 2 times	,		Repeat	ted 2 times
• [M ₁₁	M ₁₁	M ₁₂	M ₁₂	M ₁₃	M ₁₃			M _{lp}	M_{1P}
	M ₂₁	M ₂₁	M ₂₂	M ₂₂	M ₂₃	M ₂₃			M _{2P}	M_{2P}
Q/2			-	× 1		1		• • •	20	
	M _{p1}	M _{p1}	M _{P2}	Mp2	Mp3	Mp3			Mpp	Mpp
•	-1	-1	0	0	0	0	<mark></mark> .	•••	0	0
-	0	0	-1	-1	0	0			0	0
Q/2	0	0	0	0	-1	-1		•••	0	0
			1920							
	0	0	0	0	0	0			-1	-1

Figure 2(b). 2Px2P Local Wavelet Transform

1	1	1	1	1	1	1	1
1	1	1	1	-1	-1	-1	-1
1	1	-1	-1	0	0	0	0
1	-1	-1	1	0	0	0	0
1	-1	1	-1	0	0	0	0
0	0	0	0	1	1	-1	-1
0	0	0	0	1	-1	-1	1
0	0	0	0	1	-1	1	-1

Figure 3(a). 8x8 Global Walsh Wavelet Transform

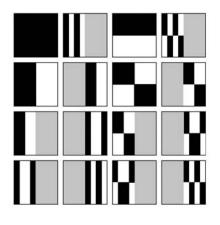


Figure 3(b). First 16 texture patterns (out of total 64) of 64-pattern Global Walsh Texture Patterns

4.2 Local Walsh Texture Pattern Generation

The 64 and 256 local Walsh texture patterns are generated using local Walsh Wavelet transform matrices of size 8x8 and 16x16 respectively. The 8x8 local Walsh wavelet transform matrix is shown as in figure 4(a), each row of this matrix is considered one at a time and is multiplied with all rows of the same matrix to generate 64 Walsh texture patterns. Figure 4(b) shows first 16 (of total 64 texture patterns) texture patterns of the 64-pattern Local Walsh texture set where black colour represent the values '1' in the pattern, grey colour represents the value '0' and values '-1' are represented by white colour. The obtained Walsh texture patterns then are resized as the size of image for which texture features have to be extracted.

1	1	1	1	1	1	1	1	
1	1	1	1	-1	-1	-1	-1	
1	1	-1	-1	-1	-1	1	1	
1	1	-1	-1	1	1	-1	-1	
1	-1	0	0	0	0	0	0	
0	0	1	-1	0	0	0	0	
0	0	0	0	1	-1	0	0	
0	0	0	0	0	0	1	-1	

Figure 4(a). 8x8 Local Walsh Wavelet Transform

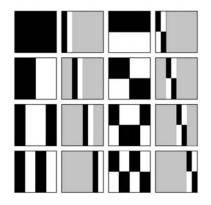


Figure 4(b). First 16 texture patterns (out of total 64) of 64-pattern Local Walsh Texture Patterns

5. CBIR Using Global and Local Texture Patterns

In all four variations of proposed CBIR method are possible using the global & local Walsh wavelet transform and the assorted texture pattern set of 64-pattern & 256pattern. For feature extraction in CBIR using texture patterns first the ternary image map is generated and then the desired texture pattern set is generated (64-pattern or 256-pattern) using the corresponding Walsh wavelet transform.

To generate feature vectors the ternary image map of the image is compared with each pattern of the generated Walsh texture patterns (Global or Local) to find the matching number of ones, zeros & minus ones. The feature vactor will have three values (number of matching '1', '0' & '-1') per pattern per colour plane in Walsh texture patterns. The per image feature vector size for Walsh texture pattern based CBIR is given by equation 12.

Feature vector size =
$$\begin{array}{c} 3^{*3*}(\text{no. of considered} \\ \text{texture pattern}) \end{array}$$
(12)

Table 1. Feature vector of image retrieval using texture patterns

CBIR Technique	64- Pattern	256- Pattern
Global Walsh Texture Patterns	192	768
Local Walsh Texture Patterns Patterns	192	768

The main advantage of proposed CBIR methods is reduced time complexity for query execution due to reduced size of feature vector resulting into faster image retrieval with better performance as compared to the colour averaging [1,2,3] based image retrieval techniques. Also the feature vector size is independent of image size in proposed CBIR methods.

6. Implementation

The implementation of the discussed CBIR techniques is done in MATLAB 7.0 using a computer with Intel Core 2 Duo Processor T8100 (2.1GHz) and 2 GB RAM. The CBIR techniques are tested on the Wang image database [18] of 1000 variable size images spread across 11 categories of human being, animals, natural scenery and manmade things, etc. The categories and distribution of the images is shown in table 2.

To assess the retrieval effectiveness, we have used the precision and recall as statistical comparison parameters [4,5] for the proposed CBIR techniques. The standard definitions for these two measures are given by the equations 13 and 14.

$$Precision = \frac{Number_of_relevant_images_retrieved}{Total_number_of_images_retrieved}$$
(13)

$$\operatorname{Re} call = \frac{Number_of_relevant_images_retrieved}{Total_number_of_relevent_images_in_database}$$
(14)

Category	Tribes	Buses	Beaches
No. of Images	85	99	99
Category	Horses	Mountains	Airplanes
No. of Images	99	61	100
Category	Dinosaurs	Elephants	Roses
No. of Images	99	99	99
Category	Monuments	Sunrise	
No. of Images	99	61	

Table 2. Image Database: Category-wise Distribution

7. Results of CBIR using Texture Patterns

The crossover point of precision-recall plays very important role in performance comparison of image retrieval methods, higher crossover point value indicates better image retrieval. The crossover point value of average precision and recall values obtained by firing 55 queries on image database are computed for proposed Walsh wavelet transform texture pattern based image retrieval methods. Figure 5 shows the performance comparison of the proposed Walsh wavelet transform based texture pattern CBIR methods with the Walsh transform based texture pattern [34] CBIR methods. It can be observed that in case of Walsh wavelet transform based texture patterns 64-pattern based CBIR technique is better than 256pattern based CBIR methods. Moreover it can be observed that the proposed CBIR methods are more efficient than the Walsh transform texture patterns as indicated by higher precision-recall crossover values. In the case of 64-pattern texture and 256-pattern texture, local Walsh texture patterns prove to be better than global Walsh texture patterns indicating that the local texture patterns contain more information about the image as compared to global texture patterns. Overall 64-pattern local Walsh wavelet transform based texture patterns give the best image retrieval among the discussed CBIR techniques as indicated by precision-recall crossover value.

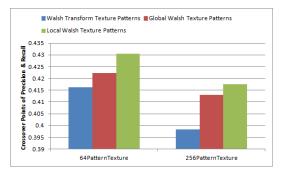


Figure 5. Performance Comparison of proposed Walsh wavelet transform based texture pattern CBIR methods with Walsh transform based texture pattern CBIR methods

8. Conclusion

The novel image retrieval methods using Walsh wavelet transform based texture patterns are presented in this paper. It has been observed that the Walsh wavelet transform based texture pattern outperform the Walsh transform based texture pattern for image retrieval. Here 64-pattern texture gives the best result beyond which the results start deteriorating indicating that texture patterns can give better results only up to a certain level. The local Walsh wavelet transform based texture patterns give better performance than the global Walsh wavelet transform based texture patterns. Among the proposed CBIR methods, 64-pattern local Walsh wavelet transform based texture patterns give better performance than other proposed methods as indicated by precision-recall crossover value.

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