

Brain Tumor Detection Approach based on Clustering with Adaptive Filter & Feedback for MRI Images

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Abstract

Brain tumor detection and its evaluation are hard tasks in clinical photograph processing due to the fact brain picture and its shape is complicated that may be analyzed simplest with the aid of expert radiologists. Image Segmentation plays an essential role within the processing of these clinical pictures. MRI (magnetic resonance imaging) has become a mainly beneficial medical diagnostic device for prognosis of brain and different clinical pictures. This paper offers a comparative take a look at of existing segmentation strategies applied for tumor detection and also presents an efficient tumor detection approach based hybrid clustering with an adaptive filter for MR images. The techniques include K- means approach clustering with watershed segmentation set of rules, optimized k-mean approach clustering with genetic algorithm and optimized subjective c-mean clustering with adaptive filter and feedback (Proposed). Traditional k-mean approach algorithm is sensitive to the initial cluster facilities. Genetic c-means and k-mean clustering techniques with adaptive filter and feedback (Proposed Hybrid) are used to come across tumor in MRI of brain pictures. The adaptive filter helps to remove undiscovered noises and feedback method help to maintain accuracy. At the stop of the procedure, the tumor is extracted from the MR picture and its precise position and the shape are determined accurately. The experimental outcomes indicate that genetic c-mean approach no longer best eliminate the over segmentation hassle, however also offer speedy and efficient clustering outcome.

Keywords:

Image segmentation, Image processing, Brain tumour, MR images, subjective Fuzzy C-Mean, Genetic Method.

1. Introduction

In Medical diagnosis, through Magnetic Resonance Images, Robustness and accuracy of the Prediction algorithms are very important, because the result is crucial for treatment of Patients. A brain tumor is a cluster of abnormal cells growing in the brain. It may occur in any person at almost any age. It may even change from one treatment session to the next but its effects may not be the same for each person. Brain tumors appear at any location, in different image intensities, can have a variety of shapes and sizes [3]. Brain tumors can be malignant or benign. Benign brain tumors have a homogeneous structure and

do not contain cancer cells. They may be either monitored radio logically or surgically destroyed completely, and they seldom grow back. There are many popular classification and clustering algorithms used for predicting the diseases from Images Figure 1.

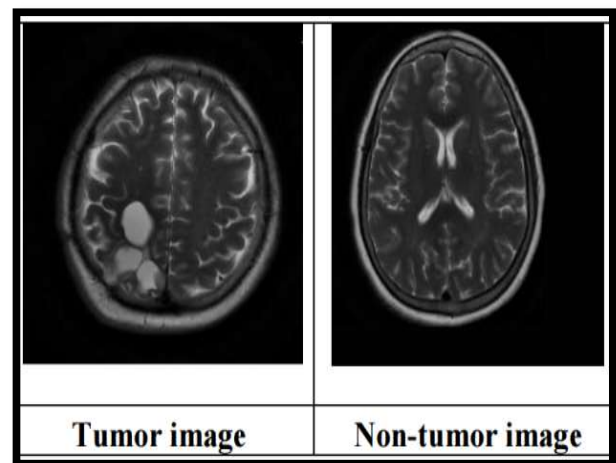


Figure 1. MRI Tumor Images

The goal of clustering a medical image is to simplify the representation of an image into a meaningful image and make it easier to analyze. Several Clustering and Classification algorithms are aimed at enhancing the Prediction accuracy of diagnosis Process in detecting abnormalities such as Cancer and white matter lesions from MR Images.

Malignant brain tumors have a heterogeneous structure and contain cancer cells. In this system, we are going to implement a technique which can classify tumor and give more accurate result. The tumor can be treated by radiotherapy, chemotherapy or a combination and they are life-threatening [4]. Therefore, for diagnosing the brain tumors in an appropriate time is highly essential for further treatments. In recent years, neurology and basic neuroscience have been significantly advanced by imaging

tools that enable in vivo monitoring of the brain. Magnetic resonance imaging (MRI) has proven to be a powerful and versatile brain imaging modality that allows non-invasive longitudinal and 3-D assessment of tissue morphology, metabolism, physiology, and function.

The information MRI provides has greatly increased the knowledge of normal and diseased anatomy for medical research and is an important component in diagnosis and treatment planning. MR imaging is currently the method of choice for early detection of a brain tumor in the human brain. However, the interpretation of MRI is largely based on radiologist's opinion.

2. Literature Survey

Paper [1] presented Integrated Multiple Features for Tumor Image Retrieval Using Classifier and Feedback Methods. This paper presents an effective approach in which the region of the object is extracted with the help of multiple features ignoring the background of the object by employing edge following segmentation method followed by extracting texture and shape characteristics of the images. The former is extracted with the help of Steerable filter at different orientations and radial Chebyshev moments are used for extracting the later.

Initially [4] the images similar to the query image are extracted from a large group of medical images. Then the search is by accelerating the retrieval process with the help of Support Vector Machine (SVM) classifier. The performance of the retrieval system is enhanced by adapting the subjective feedback method of Support Vector Machine (SVM) classifier. The performance of the retrieval system is enhanced by adapting the subjective feedback method.

Brain tumor cells have high proteinaceous fluid which has very high density and hence very high intensity, therefore watershed segmentation is the best tool to classify tumors and high-intensity tissues of the brain [7]. Watershed segmentation can classify the intensities with a very small difference also, which is not possible with snake and level set method. A similar method for tumor detection is proposed by [4], but multi-parameter extraction was not used. Paper [11] has proposed a method for brain tumor detection and segmentation using histogram thresholding detects the tumor but the result showed crops excessive area of the brain.

An efficient and improved brain tumor detection algorithm was developed by [8] which makes use of multi-parameter MRI analysis and the tumor cannot be segmented in 3-D unless and until we have 3-D MRI image data set. So, a relatively simple method for detection of brain tumor

is presented which makes use of marker-based watershed segmentation with improvement to avoid over & under segmentation.

The Segmentation of an Image [13] entails the division or separation of the image into regions of the similar attribute. The ultimate aim in a large number of image processing applications is to extract important features from the image data, from which a description, interpretation, or understanding of the scene can be provided by the machine. The segmentation of brain tumor from magnetic resonance images is an important but time-consuming task performed by medical experts. The digital image processing community has developed several segmentation methods, many of them ad hoc. Four of the most common methods are-

- Amplitude Thresholding,
- Texture Segmentation,
- Template Matching, and
- Region-growing Segmentation.

It is very important for detecting tumors, edema and necrotic tissues. These types of algorithms are used for dividing the brain images into three categories:

- Pixel based
- Region or Texture-Based
- Structural based.

When experts work on tumor images then they use three different types of algorithms. Some of the techniques based on pixel based, some based on the texture of images and some of them based on the structure of images. Paper [13], suggested an algorithm which used multi-scale image segmentation, this algorithm was based on a fuzzy c-mean algorithm for the detection of brain tumor [13].

3. Problem Identification

Besides investigating suitable frameworks for image mining, early image miners have attempted to use existing techniques to mine for image information. There are some medical image segmentation systems which use K-means algorithm for detecting a mass tumor in the brain. The following problems are faced by the existing system. Slow Detection time-Traditional K-means algorithm is sensitive to the initial cluster centers; cluster results fluctuate with different initial input and are easy to fall into a local optimum.

- Over-segmentation & Less accurate- Due to limitations of the conservative watershed algorithm

- The Volume of MRI Images cannot be calculated in existing system the Existing system, the growth rate is not calculated.

4. Hybrid Proposed Method

This paper offers a comparative take a look at of existing segmentation strategies applied for tumor detection and also presents an efficient tumor detection approach based hybrid clustering with an adaptive filter for MR images. The techniques include K- means approach clustering with watershed segmentation set of rules, optimized k-mean approach clustering with genetic algorithm and optimized subjective c-mean clustering with adaptive filter and feedback (Proposed Hybrid).

Traditional k-mean approach algorithm is sensitive to the initial cluster facilities. Genetic c-means and k-mean clustering techniques with adaptive filter and feedback (Proposed Hybrid) are used to come across tumor in MRI of brain pictures. The adaptive filter helps to remove undiscovered noises and feedback method help to maintain accuracy. At the stop of the procedure the tumor is extracted from the MR picture and its precise position and the shape are determined accurately.

4.1 Algorithm for proposed method (optimized subjective c-mean clustering with adaptive filter and feedback)-

- Step 1:** Determine the parameters of GA and generate preliminary populace randomly.
- Step 2:** Determine upper and decrease bounds of parameters.
- Step 3:** Evaluate the fitness feature of individuals of the preliminary population earlier than and after optimization.
- Step 4:** Create a new set of populations by means of the use of selection, crossover and mutation operators.
- Step 5:** Evaluate the health of people of the new populace and repeat Step four until fitness necessities are met.
- Step 6:** Obtain clustering results and follow filtering over clustering effects.
- Step 7:** Apply morphological operation and then follow a watershed algorithm to extract the tumor region.
- Step 8:** A clustering technique is used to achieve a partition of N objects using an appropriate measure together with resemblance function as a distance degree: 'd'. The approach entails following steps.
- 8.1 Choose an appropriate wide variety of clusters (say 'ok').
 - 8.2: Set initial facilities of clusters as $c_1, c_2, \dots, c_k$.

8.3 Classify every vector x into the closest center c_i through using four: Recomputed the expected cluster facilities.

8.4 If no any cluster centers adjustments then visit 8.3

Step: 9 during the user feedback phase the tumor is identified by applying edge following method followed by Mathematical Transform operation to remove the skull.

Basically, there are four morphological operations - Dilation, Erosion, Opening, closing. Proposed method adapted to obtain the tumor region. This segmented region is used as feedback information for retrieving abnormal images from the database.

5. Simulation Result Analysis

Existing method (K-Mean) and Proposed (GA-based Subjective feedback) method both are implemented over MATLAB simulator and following results are calculated.

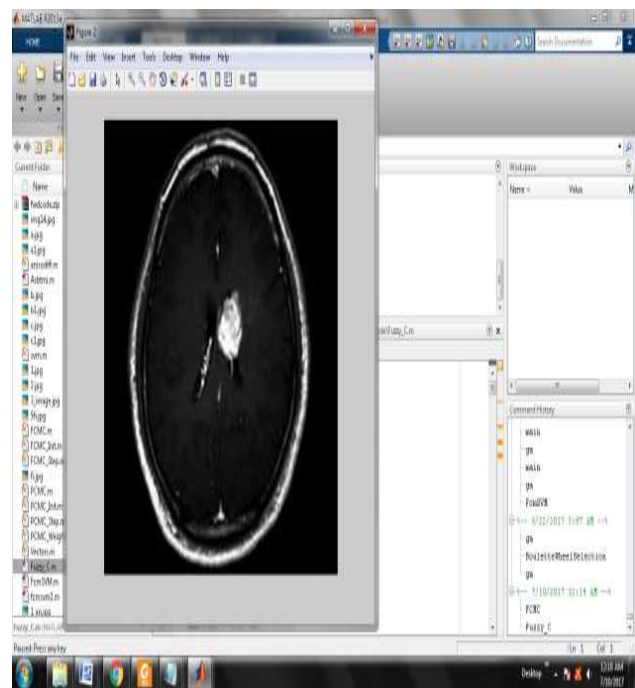
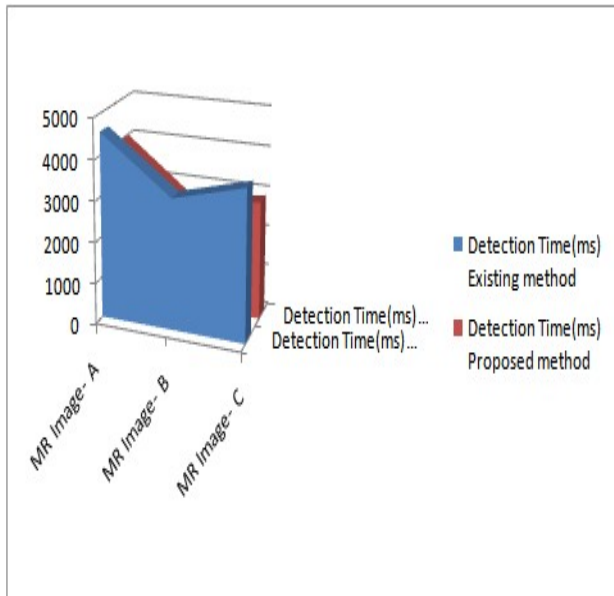


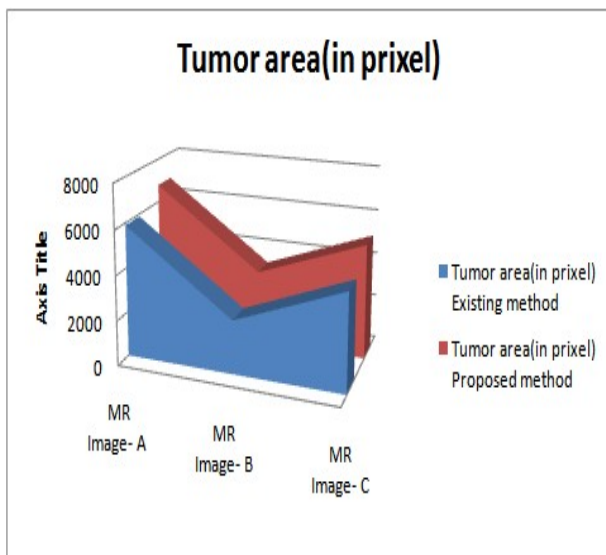
Figure 5 Simulation of proposed method

5.1 Detection Time- Searching time gives us how much time it takes for a segmentation method to generate the output.



5.2 Tumour detection region- Area of an image is calculated by knowing the vertical and horizontal resolution of an image.

Area of tumour = vertical resolution * horizontal resolution * Total no of pixels in infected area



6. Conclusion and Future Works

In medical images, the image segmentation plays an important role. Today's many extensive methodologies are available for medical diagnoses like CT scan and MRI. The different method is used in image mining techniques for detecting the brain tumor like K-means, C-Means and much more. But all the techniques have some disadvantages. Like K-means algorithm not properly segment which images have been corrupted by noise. And doses do not calculate the volume and growth rate of the tumor. In this work proposed method achieves better detection rate and quality over existing method. In future, we will implement this setup for a real-time system with the cloud which will more efficient.

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